

**Computational Algebraic
Geometry Methods
with Applications to
Synchronization
and
Power Flow
Equations**

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Complex Systems: Synchronization



**Fireflies at the Smoky Mountains (Gatlinburg, Tennessee, USA).
Courtesy: www.gatlinburgtnguide.com**

Complex Systems: Synchronization



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Complex Systems: Synchronization



Rhythmic applause

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Complex Systems: Synchronization



Power networks and electrical grids.

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Complex Systems: Synchronization



Neural network synchronization

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Complex Systems: Synchronization

The Kuramoto Model:

$$\frac{d\theta_i}{dt} = \omega_i + \frac{K}{N} \sum_{j=1}^N \sin(\theta_i - \theta_j), \text{ for } i = 1, \dots, N$$

ω_i are normal frequencies

i.e. the frequency without the presence of the sine terms.

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- Each oscillator (firefly) *knows* what all other oscillators are doing, called the complete graph.
- One can also have other more realistic graphs, e.g., random, cyclic, small-world, etc.

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- 'K' is the *strength/amount of knowledge* about other oscillators.
- In this set up, each oscillator has the same amount of knowledge about others as all others.
- One can also have a setup with different values of K for each pair of oscillators and so on.

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- when $K=0$, all oscillators oscillate with their natural frequencies
- increasing K from 0, the oscillators start working together
- but only at a particular value of K , they are synchronized

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$K < K_c$, no synchronization

$K \geq K_c$, synchronization

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Problems:

1. Dependent on initial conditions
2. multiple stable steady states
3. Dependent on step size
4. No stable steady state?

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A different mathematical set up of the problem:

- **Find the first instance of K, starting from K=0, for which the below system has at least one stable steady state.**

$$\omega_i + \frac{K}{N} \sum_{j=1}^N \sin(\theta_i - \theta_j) = 0, \text{ for } i = 1, \dots, N$$

Complex Systems: Synchronization

The Kuramoto Model (power flow equations for lossless network with all nodes being PV nodes):

$$\omega_i + \frac{K}{N} \sum_{j=1}^N \sin(\theta_i - \theta_j) = 0, \text{ for } i = 1, \dots, N$$

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Polynomial equations → Algebraic Geometry → Computations

An Example

$$x z - 3 y + 1 = 0$$

$$x^2 - 2 y = 0$$

$$x y - 5 = 0$$

Solve for x, y, z .

Two methods:

1. Groebner Basis Method

2. Numerical Algebraic Geometry

Groebner Basis

- Very roughly speaking, one can obtain another system of polynomial equations by performing a finite set of operations on the original system (the Buchberger algorithm with lexicographic monomial ordering)
- The new system is 'easier' to solve
- The new system has the same solutions as the original
- The new system is called the Groebner basis
- Packages like Singular, COCOA, MACAULAY2, MAGMA, Maple, Mathematica, etc.
- The first three are available for free !!

How is it useful?

For the running example, Mathematica gives (lexicographic monomial ordering)

$$x^3 - 10 = 0$$

$$-x^2 + 2y = 0$$

$$x^2 - 15x + 10z = 0$$

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Back-substitute the three solutions in the rest of the system

There are 3 solutions: 1 real + 2 complex

Numerical Algebraic Geometry/ Homotopy Continuation Method

1. Estimate an upper bound of the number of solutions of the system to be solved.

e.g.,

Bezout bound = product of degrees of all the polynomials in the system.
= $2 \times 2 \times 2 = 8$, for our running example

$$\vec{f}(x, y, z) = (x z - 3 y + 1, x^2 - 2 y, x y - 5)^T$$

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2. Construct a new system in the same variables
 - (a) which has the same no. of solutions as the estimated upper bound,
 - (b) easy to solve

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$$\vec{g}(x, y, z) = (x^2 - 1, y^2 - 1, z^2 - 1)^T$$

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3. Track each solution of the new system using

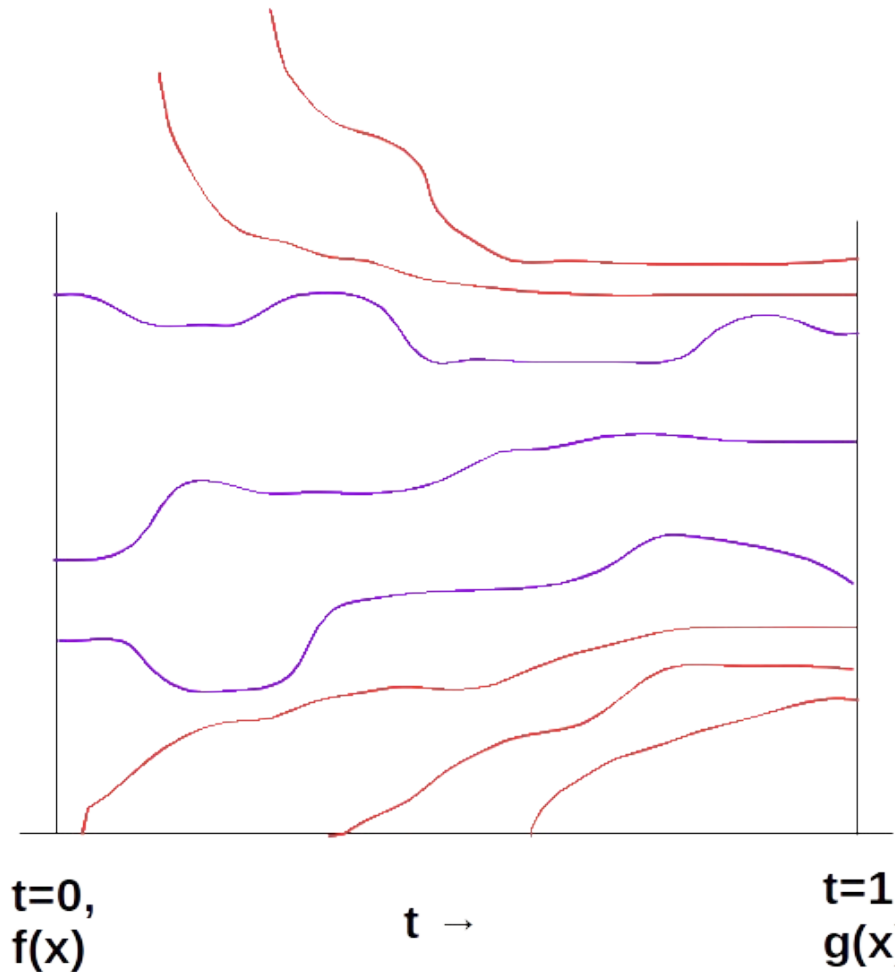
$$\vec{H}((x, y, z), t) = (1 - t)\vec{f}(x, y, z) + e^{i\gamma t}\vec{g}(x, y, z) = 0$$

from $t=1$ to $t=0$, using predictor-corrector or any other method.

If a solution of the new system converges to the original one at $t=0$, then it is a solution, otherwise not.

Note that 'gamma' is a generic real number, and is important here.

Numerical Algebraic Geometry/ Homotopy Continuation Method



Numerical Algebraic Geometry/ Homotopy Continuation Method

There are well-written packages available for free:

Bertini, HOM4PS2, PHCPack.

Groebner Basis

- 1. Exact solutions**
- 2. Exponential space complexity**
- 3. Highly sequential**
- 4. Non-integer coefficients a problem**

Numerical Algebraic Geometry

Numerical, but ALL solutions/extrema

No such scaling problems

'Embarrassingly' parallelizable

Floating point coefficients are fine

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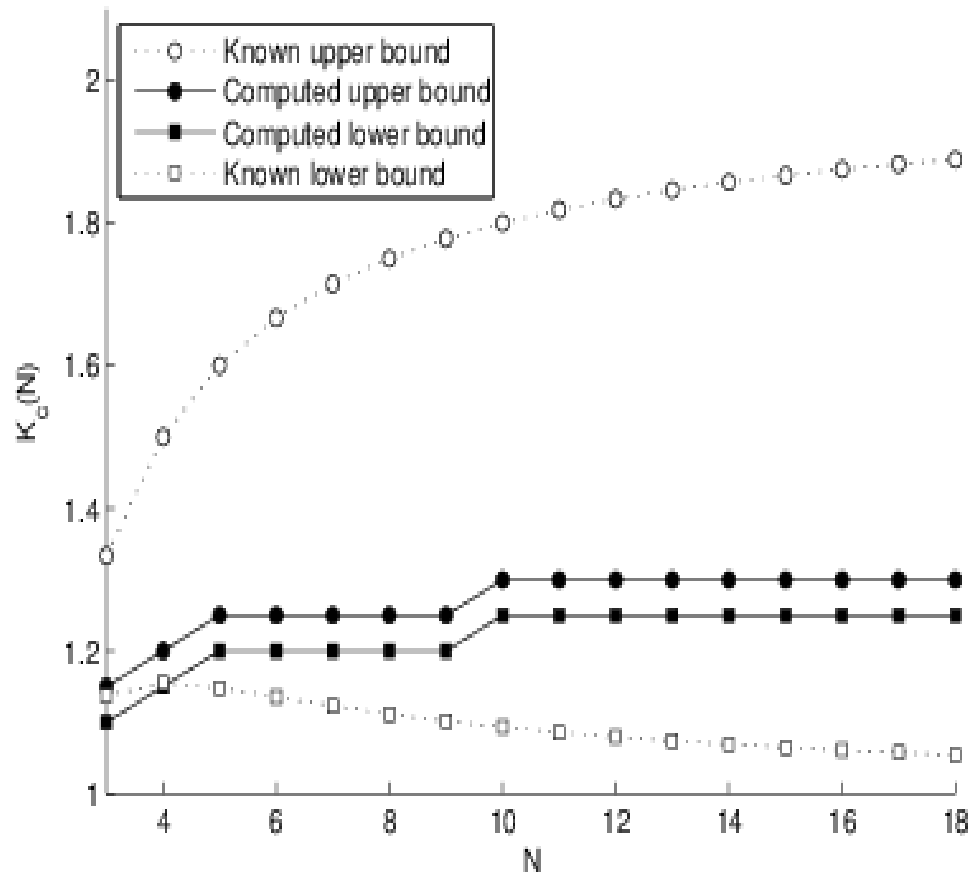
Caution: The Groebner basis methods can work exceptionally well in many cases (e.g., Sudoku) ...

Complex Systems: Synchronization

Solve (DM, Noah Daleo, Jonathan D Hauenstein, Florian Doerfler):

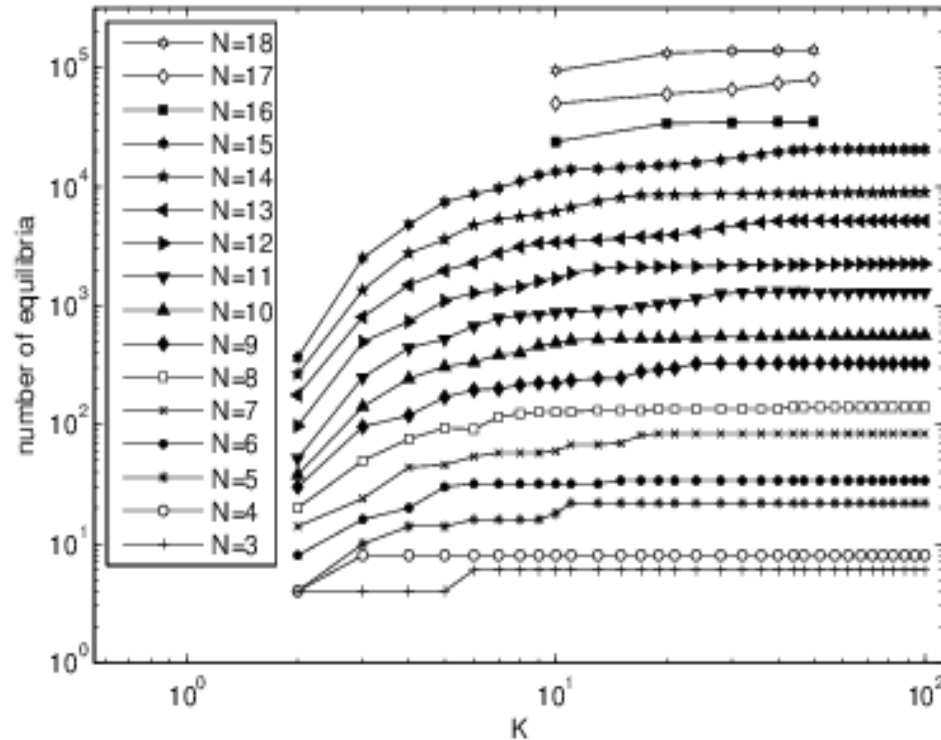
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Complex Systems: Synchronization (For equidistant frequencies)



DM, Noah Daleo, Jonathan D Hauenstein, Florian Doerfler. 2015.

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Complex Systems: Synchronization (For equidistant frequencies)

Conjecture [Araposthatis et al., 1981]: if there is a stable equilibrium, then there is a stable equilibrium with

$$|\theta_i - \theta_j| < \frac{\pi}{2}, \text{ for all neighbours } i, j.$$

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Disproved by counter-example.

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Disproved by counter-example.

- Other results for the complete graph
- Results for other graphs (cyclic, Erdos-Renyi random graph, etc.)
- In future, other graphs, eigenvalue analysis, stochastic versions of the Kuramoto model

Power Flow Problem

- In addition to the Kuramoto model
- Power flow equations: flow of power in an interconnected system

$$0 = -P_i + \sum_{k=1}^n G_{ik} (V_{iRe} V_{kRe} + V_{iIm} V_{kIm}) + \sum_{k=1}^n B_{ik} (V_{kRe} V_{iIm} - V_{iRe} V_{kIm});$$

$$0 = Q_i + \sum_{k=1}^n G_{ik} (V_{kRe} V_{iIm} - V_{iRe} V_{kIm}) - \sum_{k=1}^n B_{ik} (V_{iRe} V_{kRe} + V_{iIm} V_{kIm})$$

- B (real part of the bus admittance matrix), G (imaginary part of the bus admittance matrix), P (net power injected) and Q (net reactive power injected) are parameters.
- Solutions are important for determining the best operation of the system as well as planning future expansions on the system, etc.

Power Flow Problem

- Found all the steady states for up to $n \leq 14$ bus system (IEEE test systems) DM, K Turitsyn and H Nguyen, 2014. The first ever complete database of equilibria.
- Multistability in wind energy systems. S Chandra, DM, A Chakraborty. 2014, 2015, 2016.
- Network topology dependent upper bound on the number of power flow equilibria. DM, T Chen, D Molzahn, M Niemerg. 2015, 2016.

Current and Future Works

- Further work on *graph topology dependent* upper bounds on both complex and real power flow and Kuramoto equilibria
- Novel computational algebraic geometry methods such as discriminant variety to identify all the solution-boundaries (where the Jacobian is singular)
- Novel (non-polynomial) and tailor-made homotopy continuation methods to find stable and type-1 solutions
- Dynamical systems on graphs
- Optimal Power Flow Problem with polynomial homotopy continuation
- Machine learning (artificial neural networks and deep learning)
- Belief Propagation (probabilistic graphical models), etc.
- Computer vision.